

**SILICON RECTIFIER DIODES**



Plastic-encapsulated rectifier diodes intended for power rectifier applications.  
Normal and reverse polarity types are available.

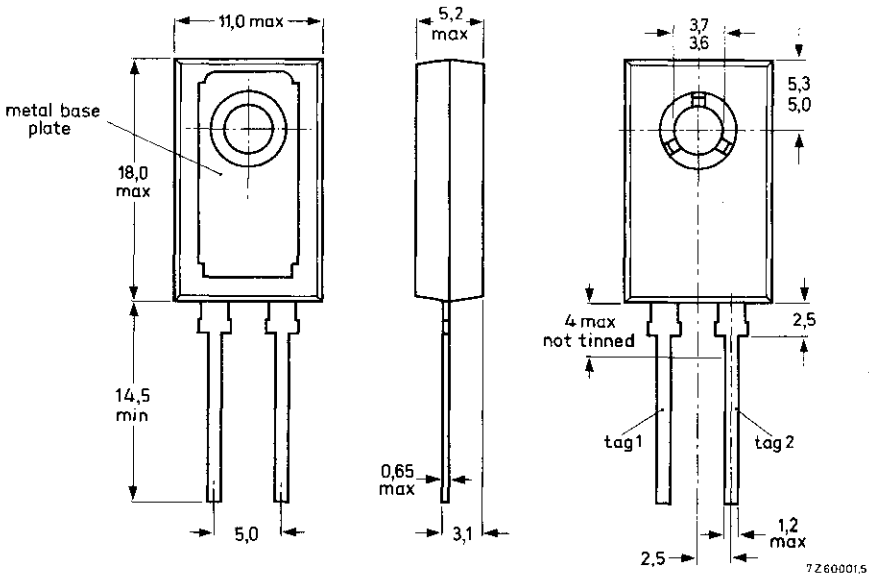
**QUICK REFERENCE DATA**

		BYX49-300(R)	600(R)	1200(R)	
Repetitive peak reverse voltage	$V_{RRM}$	max. 300	600	1200	V
Average forward current	$I_{F(AV)}$		max. 6		A
Non-repetitive peak forward current	$I_{FSM}$		max. 40		A

**MECHANICAL DATA** (see also page 2)

Dimensions in mm

SOD-38



The exposed metal base-plate is directly connected to tag 1.

Products approved to CECC 50 009-011, available on request

**MECHANICAL DATA** (continued)

Net mass: 2,5 g

Recommended diameter of fixing screw: 3,5 mm

Torque on screw

when using washer and heatsink compound: min. 0,95 Nm (9,5 kg cm)  
max. 1,5 Nm (15 kg cm)

Accessories:

supplied with device: washer

available on request: 56316 (mica insulating washer)

**POLARITY OF CONNECTIONS**

	BYX 49-300 to BYX 49-1200	BYX 49-300R to BYX 49-1200R
Base-plate:	cathode	anode
Tag 1 :	cathode	anode
Tag 2 :	anode	cathode

All information applies to frequencies up to 400 Hz.

**RATINGS** Limiting values in accordance with the Absolute Maximum System (IEC134)

<u>Voltages</u>		BYX49-300(R)	600(R)	1200(R)	
Continuous reverse voltage	$V_R$	max. 200	400	800	V
Crest working reverse voltage	$V_{RWM}$	max. 200	400	800	V
Repetitive peak reverse voltage ( $\delta = 0,01$ )	$V_{RRM}$	max. 300	600	1200	V
Non-repetitive peak reverse voltage ( $t \leq 10$ ms)	$V_{RSM}$	max. 300	600	1200	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 85^\circ\text{C}$	$I_{F(AV)}$	max. 6,0	A
at $T_{mb} = 120^\circ\text{C}$	$I_{F(AV)}$	max. 3,0	A
without heatsink; at $T_{amb} = 50^\circ\text{C}$	$I_{F(AV)}$	max. 1,1	A
Forward current (d. c.)	$I_F$	max. 9,5	A
R. M. S. forward current	$I_{F(RMS)}$	max. 9,5	A
Repetitive peak forward current	$I_{FRM}$	max. 20	A
Non-repetitive peak forward current ( $t = 10$ ms; half sine wave) $T_j = 150^\circ\text{C}$ prior to surge	$I_{FSM}$	max. 40	A
$I^2t$ for fusing ( $t = 10$ ms)	$I^2t$	max. 8,0	$\text{A}^2\text{s}$

Temperatures

Storage temperature	$T_{stg}$	-55 to +125	$^\circ\text{C}$
Junction temperature	$T_j$	max. 150	$^\circ\text{C}$

**THERMAL RESISTANCE**

From junction to mounting base

$$R_{th\ j-mb} = 4,5 \text{ } ^\circ\text{C/W}$$

Transient thermal impedance;  $t = 1 \text{ ms}$

$$Z_{th\ j-mb} = 0,3 \text{ } ^\circ\text{C/W}$$

**Influence of mounting method :**

1. Heatsink mounted

From mounting base to heatsink

- a. with heatsink compound
- b. with heatsink compound and 56316 mica washer
- c. without heatsink compound
- d. without heatsink compound; with 56316 mica washer

$$R_{th\ mb-h} = 1,5 \text{ } ^\circ\text{C/W}$$

$$R_{th\ mb-h} = 2,7 \text{ } ^\circ\text{C/W}$$

$$R_{th\ mb-h} = 2,7 \text{ } ^\circ\text{C/W}$$

$$R_{th\ mb-h} = 5 \text{ } ^\circ\text{C/W}$$

2. Free air operation

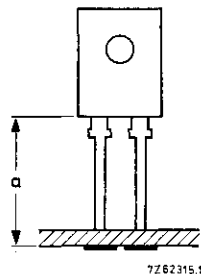
The quoted values of  $R_{th\ j-a}$  should be used only when no other leads run to the tie-points.

From junction to ambient in free air mounted on a printed circuit board at  $a =$  maximum lead length and with a copper laminate

- a.  $> 1 \text{ cm}^2$
- b.  $< 1 \text{ cm}^2$

$$R_{th\ j-a} = 50 \text{ } ^\circ\text{C/W}$$

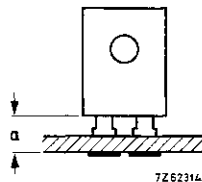
$$R_{th\ j-a} = 55 \text{ } ^\circ\text{C/W}$$



- at a lead-length  $a = 3 \text{ mm}$  and with a copper laminate
- c.  $> 1 \text{ cm}^2$
  - d.  $< 1 \text{ cm}^2$

$$R_{th\ j-a} = 55 \text{ } ^\circ\text{C/W}$$

$$R_{th\ j-a} = 60 \text{ } ^\circ\text{C/W}$$



**CHARACTERISTICS**Forward voltage

$$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 2,3 \text{ V } ^1)$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$I_R < 200 \text{ } \mu\text{A}$$

**SOLDERING AND MOUNTING NOTES**

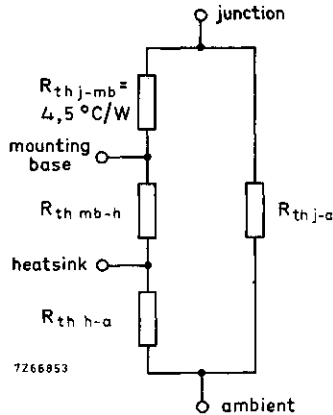
1. Soldered joints must be at least 2,5 mm from the seal.
2. The maximum permissible temperature of the soldering iron or bath is 270 °C; contact with the joint must not exceed 3 seconds.
3. The devices should not be immersed in oil, and few potting resins are suitable for re-encapsulation. Advice on these materials is available on request.
4. Leads should not be bent less than 2,5 mm from the seal; exert no axial pull when bending.
5. For good thermal contact heatsink compound should be used between base-plate and heatsink.

<sup>1)</sup> Measured under pulse conditions to avoid excessive dissipation.

**OPERATING NOTES**

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated below:



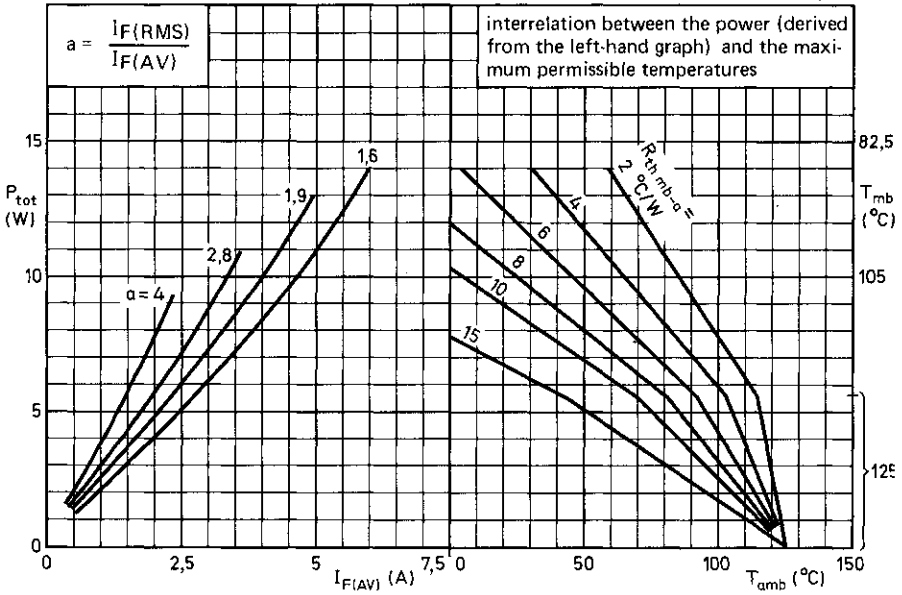
- b. The method of using the graph on page 7 is as follows:  
Starting with the curve of maximum dissipation as a function of  $I_F(AV)$ , for a particular current value trace upwards to meet the appropriate form factor curve. Trace horizontally until the  $R_{th\ mb-a}$  curve is reached. Trace horizontally until the  $T_{amb}$  scale. The intersection determines the  $R_{th\ mb-a}$  required.  
The heatsink thermal resistance value ( $R_{th\ h-a}$ ) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

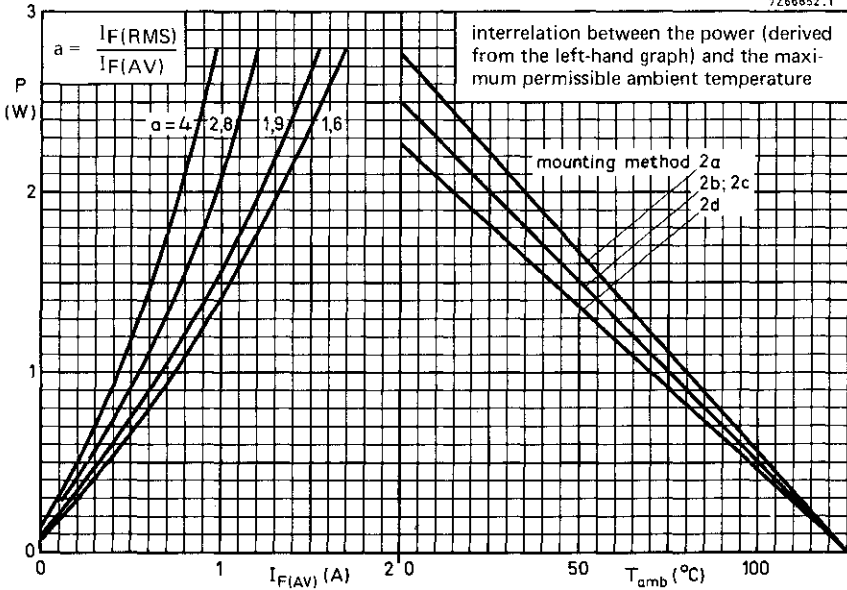
Any measurement of heatsink temperature should be made immediately adjacent to the device.

- c. The heatsink curves are optimised to allow the junction temperature to run up to  $150\ ^\circ C$  ( $T_{jmax}$ ) whilst limiting  $T_{mb}$  to  $125\ ^\circ C$  (or less).

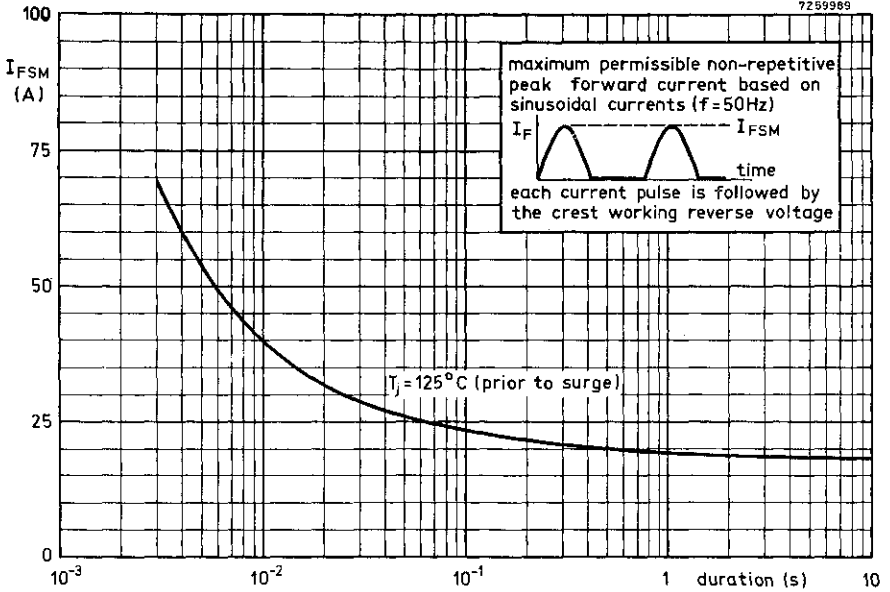
7Z59990.2



7Z66852.1



7259969



72599681

